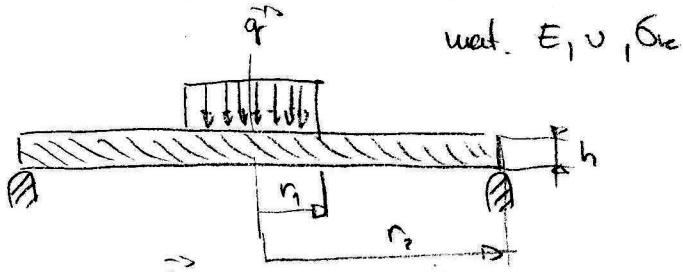
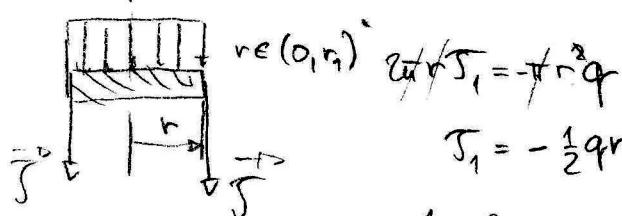


Příklad: Určete bezpečnostní MS pravovýsti



$$\int r k u r dr = \begin{cases} u = kur \Rightarrow u' = \frac{1}{r} \\ v = r \Rightarrow v = \frac{1}{2} r^2 \end{cases} = \frac{1}{2} r^2 k u r - \int \frac{1}{r} \cdot \frac{1}{2} r^2 dr = \frac{1}{2} r^2 k u r - \frac{1}{4} r^2 = \frac{1}{2} r^2 (k u r - \frac{1}{2})$$

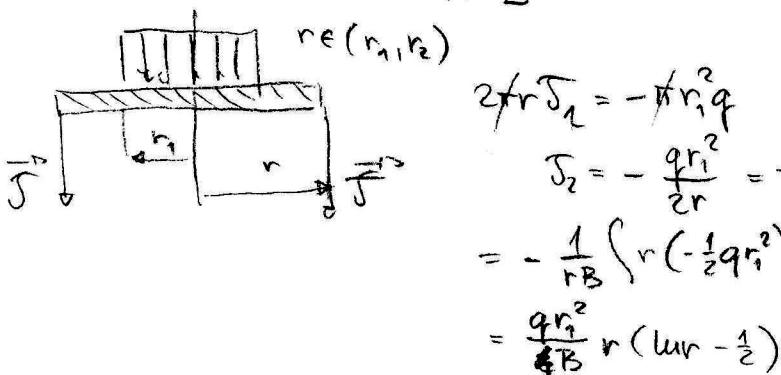
$$(\frac{1}{2} r^2 (k u r - \frac{1}{2}))' = r (k u r - \frac{1}{2}) + \frac{1}{2} r^2 \cdot \frac{1}{r} = r k u r$$



$$\tau_{p1} = -\frac{1}{2} q r \Rightarrow \delta_{p1} = -\frac{1}{r B} \int r \left(-\frac{1}{2} q r \right) dr dr =$$

$$= -\frac{1}{r B} \int r \left(-\frac{1}{2} q \right) \frac{r^2}{2} dr = +\frac{1}{r B} \frac{1}{4} q \int r^3 dr = \frac{q}{4 B} \frac{r^4}{4} =$$

$$= \frac{1}{16} \frac{q r^3}{B}$$



$$2 \int r \tau_{p2} = -\pi r_1^2 q$$

$$\tau_{p2} = -\frac{q r_1^2}{2 r} \Rightarrow \delta_{p2} = -\frac{1}{r B} \int r \left(-\frac{1}{2} q r_1^2 \frac{1}{r} \right) dr dr =$$

$$= -\frac{1}{r B} \int r \left(-\frac{1}{2} q r_1^2 \right) k u r dr = \frac{q r_1^2}{2 r B} \cdot \frac{1}{2} r^2 (k u r - \frac{1}{2}) =$$

$$= \frac{q r_1^2}{4 B} r (k u r - \frac{1}{2})$$

$$\omega_1 = C_1^1 r + \delta_{p1} = C_1^1 r + \frac{q}{16 B} r^3$$

$$w_1 = \int \omega_1 dr + C_3^1 = \int \left(C_1^1 r + \frac{q}{16 B} r^3 \right) dr + C_3^1 = C_1^1 \frac{1}{2} r^2 + \frac{q}{16 B} \frac{r^4}{4} + C_3^1 = \frac{1}{2} C_1^1 r^2 + \frac{q}{64 B} r^4 + C_3^1$$

$$\omega_2 = C_1^2 r + C_2^2 \frac{1}{r} + \delta_{p2} = C_1^2 r + C_2^2 \frac{1}{r} + \frac{q r_1^2}{4 B} r (k u r - \frac{1}{2})$$

$$w_2 = \int \omega_2 dr + C_3^2 = \int \left(C_1^2 r + C_2^2 \frac{1}{r} + \frac{q r_1^2}{4 B} r (k u r - \frac{1}{2}) \right) dr + C_3^2 = \frac{1}{2} C_1^2 r^2 + C_2^2 k u r + \frac{q r_1^2}{4 B} \left[\frac{1}{2} r^2 (k u r - \frac{1}{2}) - \frac{1}{6} r^2 \right] = \frac{1}{2} C_1^2 r^2 + C_2^2 k u r + \frac{q r_1^2}{4 B} \frac{1}{2} r^2 (k u r - 1) + C_3^2$$

$$\frac{d \omega_1}{dr} = C_1^1 + \frac{3 q}{16 B} r^2$$

$$\frac{d \omega_2}{dr} = C_1^2 - C_2^2 \frac{1}{r^2} + \frac{q r_1^2}{4 B} \left[k u r - \frac{1}{2} + \nu \cdot \frac{1}{r} \right] = C_1^2 - C_2^2 \frac{1}{r^2} + \frac{q r_1^2}{4 B} \left(k u r + \frac{1}{2} \right)$$

$$M_{r1} = -B \left(\frac{d \omega_1}{dr} + \nu \frac{\omega_1}{r} \right) = -B \left(C_1^1 + \frac{3 q}{16 B} r^2 + \nu \left(C_1^1 + \frac{q}{16 B} r^2 \right) \right) = -B \left[C_1^1 (1+\nu) + \frac{q}{16 B} r^2 (3+\nu) \right]$$

$$M_{r2} = -B \left(\frac{d \omega_2}{dr} + \nu \frac{\omega_2}{r} \right) = -B \left(C_1^2 - C_2^2 \frac{1}{r^2} + \frac{q r_1^2}{4 B} (k u r + \frac{1}{2}) + \nu \left(C_1^2 + C_2^2 \frac{1}{r^2} + \frac{q r_1^2}{4 B} (k u r - \frac{1}{2}) \right) \right) = -B \left[C_1^2 (1+\nu) + C_2^2 (-1+\nu) \frac{1}{r^2} + \frac{q r_1^2}{4 B} (1+\nu) k u r + \frac{q r_1^2}{8 B} (1-\nu) \right]$$

$$\text{Ober. pos. : } w_2|_{r=r_2} = 0$$

$$\text{pos. komp. : } w_1|_{r=r_1} = w_2|_{r=r_2}$$

$$M_{r_2}|_{r=r_2} = 0$$

$$\vartheta_1|_{r=r_1} = \vartheta_2|_{r=r_2}$$

$$M_{r_1}|_{r=r_1} = M_{r_2}|_{r=r_2}$$

$$M_{r_2}|_{r=r_2} = -B \left[C_1^2(1+v) + C_2^2(1+v) \frac{1}{r_2^2} + \frac{qr_1^2}{4B}(1+v)lur_2 + \frac{qr_1^2}{8B}(1-v) \right] = 0$$

$$\vartheta_1|_{r=r_1} = e_1^1 r_1 + \frac{q}{16B} r_1^3 = e_1^2 r_1 + C_2^2 \frac{1}{r_1} + \frac{qr_1^2}{4B} r_1 (lur_1 - \frac{1}{2}) = \vartheta_2|_{r=r_1}$$

$$M_{r_1}|_{r=r_1} = -B \left[C_1^2(1+v) + \frac{q}{16B} r_1^2(3+v) \right] = -B \left[C_1^2(1+v) + C_2^2(-1+v) \frac{1}{r_1^2} + \frac{qr_1^2}{4B}(1+v)lur_1 + \frac{qr_1^2}{8B}(1-v) \right] = M_{r_2}|_{r=r_1}$$

$$\begin{aligned} C_1^2 r_1^2 - C_1^2 r_1^2 - C_2^2 &= \underbrace{-\frac{q}{16B} r_1^4 + \frac{qr_1^4}{4B} (lur_1 - \frac{1}{2})}_{b_1} \\ C_1^2 r_2^2 (1+v) - C_2^2 (1-v) &= \underbrace{-\frac{q}{4B} r_1^2 r_2^2 (1+v) lur_2 + \frac{q}{8B} r_1^2 r_2^2 (1-v)}_{b_2} \\ C_1^2 r_1^2 (1+v) - C_1^2 r_1^2 (1+v) + C_2^2 (1-v) &= \underbrace{-\frac{q}{16B} r_1^4 (3+v) + \frac{qr_1^4}{4B} (1+v) lur_1 + \frac{qr_1^4}{8B} r_1^4}_{b_3} \end{aligned}$$

$$C_1^2 r_1^2 - C_1^2 r_1^2 - C_2^2 = b_1$$

$$C_1^2 r_2^2 (1-v) - C_2^2 (1-v) = b_2 \Rightarrow C_1^2 = \frac{1}{r_2^2 (1-v)} [b_2 + C_2^2 (1-v)]$$

$$C_1^2 r_1^2 (1+v) - C_1^2 r_1^2 (1+v) + C_2^2 (1-v) = b_3$$

$$C_1^2 r_1^2 - \frac{1}{r_2^2 (1-v)} [b_2 + C_2^2 (1-v)] \cdot r_1^2 - C_2^2 = b_1$$

$$C_1^2 r_1^2 (1+v) - \frac{1}{r_2^2 (1-v)} [b_2 + C_2^2 (1-v)] r_1^2 (1+v) + C_2^2 (1-v) = b_3$$

$$\Rightarrow C_1^2 = \frac{1}{r_1^2} b_1 + \frac{1}{r_2^2 (1-v)} b_2 + C_2^2 \left[\frac{1}{r_1^2} + \frac{1}{r_2^2} \right]$$

$$\left[\frac{1}{r_1^2} b_1 + \frac{1}{r_2^2 (1-v)} b_2 + C_2^2 \left[\frac{1}{r_1^2} + \frac{1}{r_2^2} \right] \right] r_1^2 (1+v) - \frac{r_1^2 (1+v)}{r_2^2 (1-v)} b_2 - C_2^2 \frac{r_1^2 (1+v)}{r_2^2} +$$

$$+ C_2^2 (1-v) = b_3 \Rightarrow C_2^2 \left[(1+v) + \frac{r_1^2}{r_2^2} (1+v) - \frac{r_1^2}{r_2^2} (1+v) + (1-v) \right] =$$

$$= -(1+v) b_1 - \frac{r_1^2 (1+v)}{r_2^2 (1-v)} b_2 + \frac{r_1^2 (1+v)}{r_2^2 (1-v)} b_2 + b_3 \Rightarrow$$

$$\boxed{C_2^2 = -(1+v) b_1 + b_3}$$

$$C_1' = \frac{1}{r_1^2} b_1 + \frac{1}{r_2^2(1-\nu)} b_2 + (-(\nu+1)b_1 + b_3) \left(\frac{1}{r_1^2} + \frac{1}{r_2^2} \right) \Rightarrow$$

$$\Rightarrow C_1' = \left(-\frac{\nu}{r_1^2} - \frac{1+\nu}{r_2^2} \right) b_1 + \frac{1}{r_2^2(1-\nu)} b_2 + \left(\frac{1}{r_1^2} + \frac{1}{r_2^2} \right) b_3$$

$$C_1^2 = \frac{1}{r_2^2(1-\nu)} [b_2 + [-(1+\nu)b_1 + b_3](1-\nu)] \Rightarrow$$

$$\Rightarrow C_1^2 = -\frac{1+\nu}{r_2^2} b_1 + \frac{1}{r_2^2(1-\nu)} b_2 + \frac{1}{r_2^2} b_3$$

$$\sigma_{r,\omega} = \pm \frac{6M_r}{h^2} \quad , \quad \sigma_{t,\omega} = \pm \frac{6M_t}{h^2} \quad , \quad B = \frac{Eh^3}{12(1-\nu^2)}$$